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A direct machine-specific parameters incorporated Spot-scanning Proton Arc (SPArc) algorithm

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Disclosure:



- The study in part is supported by Ion Beam Application S.A.
- There is an issued patent related to the proton arc therapy





Purpose



- Challenges:
 - Each proton system has its own spot irradiation sequence
 - Each gantry or couch has its mechanical limitations
- To address the challenges of generating a deliverable and efficient SPArc plan for a specific proton therapy system.







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- Incorporate the machine-specific parameters (machine limitation and spot delivery sequence) into SPArc optimization
- SPArc delivery sequence (DSM_{arc}) modelling
 - (a) machine specific parameter modelling
 - including maximum gantry speed, acceleration, and deceleration speed
 - (b) irradiation parameter modelling
 - including energy switching and spot switching, spot delivery sequence and time
- SPArc delivery sequence (DSM_{arc}) can predict gantry rotation speed and beam status(ON/OFF) accurately.





 The gantry angle vs. delivery time showed a good agreement between the DSM_{arc} and log file.(delivery time difference:6.1%±3.9% on average for eight cases)







• 3D gamma pass ratio with criteria 3mm, 3% between reconstructed dose and initial plan dose are greater then 98% for all validated cases.





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• SPArc_{DMSP} resamples and adjusts each control point's delivery speed based on the DSM_{arc} calculation through the iterative approach.



Framework of SPArc_{DMSP} iterative optimization algorithm.

a.Control point resample;
b.Energy layer redistribution and filtration;
c.Predict delivery time and gantry rotation speed per control point;
d.Spot redistribution and spot intensity modulation e.Spot filtration



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- Four representative cases(brain, head neck, liver and lung cancer patients) were selected to test SPArc_{DMSP.}
- Two kinds of SPArc plans were generated using the same planning objective functions:
- A.SPArc_{DMSP} plan meeting the maximum allowable gantry acceleration speed(0.6deg/s²);
- B.SPArc_{DMSP-user-speed} plan with a user pre-defined delivery time and constraint the acceleration speed<0.1deg/s².
- Simulated arc delivery sequence based on the DSM_{arc} was compared.



Abbreviation: A: spot-scanning proton arc(SPArc) incorporated mechanical maximum allowable constraints (0.6deg/s²) and delivery sequence (SPArc_{DMSP}),

Result

B: SPArc_{DMSP-user-speed} with user predefined treatment delivery speed and gantry acceleration constraint <0.1deg/s².

• The plan parameters(object	ctive value, total ene	ergy layers,spots,
delivery time) are similar.	Number	Cost

No.	Numb Plan of Model Energ Laye	Number of Numb		r Delivery s Time(s)	Cost Function Value	Gantry Velocity		
			Number			Mean (degree/s)	Standard Deviation	
		Energy Layer	of Spots				Absolute (degree/s)	Relative
1	А	37	2577	137	0.0663	0.73	0.17	23.78%
	В	37	2294	122	0.0762	0.73	0.06	8.44%
2	А	36	2981	140	1.55	0.67	0.16	24.09%
	В	35	2453	146	1.6935	0.69	0.07	10.24%
3	А	38	10272	269	0.4502	0.38	0.04	10.19%
	В	38	9158	262	0.422	0.39	0.03	7.20%
4	А	36	7362	208	0.8585	0.48	0.18	37.19%
	В	36	7322	221	0.7805	0.45	0.06	12.35%

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Result



Plan quality is similar.



A slice dose of a head neck case for (a) SPArc_{DMSP-user-speed} (b) SPArc_{DMSP} (c) the corresponding DVH comparison (d) dose difference.



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Result



The SPArc_{DMSP-user-speed} plan could minimize the gantry momentum change based on clinical users input compared to the SPArc_{DMSP}.



The comparison of gantry velocity and gantry angle vs time for $SPArc_{DMSP}$ (dash line) and $SPArc_{DMSP-user-speed}$ (solid line) using a head neck cancer case as an example.



Conclusion



- SPArc-DSM_{arc} plan could meet the mechanical constraint of the specific proton system.
- Additionally, SPArc-DSM_{arc} can directly optimize the treatment speed and momentum changes of the gantry in the plan optimization process.
- This work paved the roadmap for the clinical implementation of proton arc therapy in the treatment planning system.







Thanks!

